

MOTINOVA Mid-Motor Communication Protocol (Iot Device)

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2022-02-16

Modification Record

Modification Date	Modified By	Content	Version
20220216	Dail	First published	V1.0

MOTINOVA Mid-Motor Communication Protocol (Iot Device)

1 System Composition

MC: Motor Controller

BMS: Battery Management System

PBU: Push Button Unit

HMI: Human Machine Interface

Iot Device: Device for connecting to internet

APP: Application

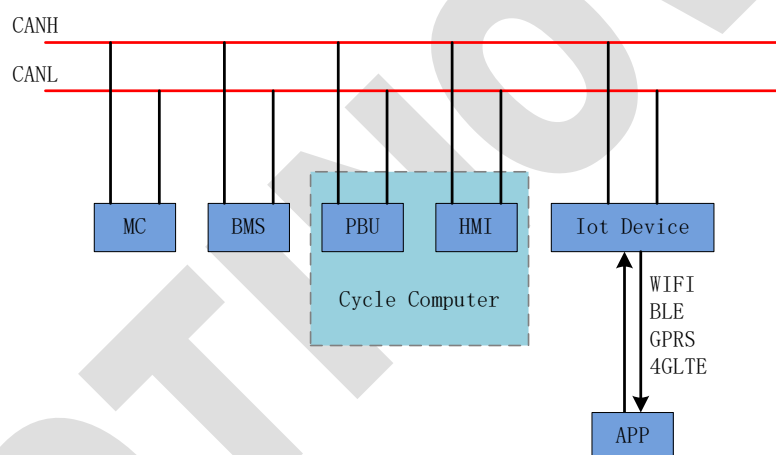


Figure 1 Communication Connector Graph

2 Communication Protocol Regulations

This protocol is mainly describing the format of data communication between the components of MOTINOVA mid-motor driving system which is only applicable to MOTINOVA.

2.1 Hardware Interface

Interface Type: CAN2.0A

Baud Rate: 125Kbps / 250Kbps (Option, default by 125Kbps)

2.2 Data Frame Packing

2.2.1 Data frame format

This protocol is describing data content of each frame, including frame head,

command segment length, command word, data segment, check bit and frame end.

Frame Format as below:

Table 1 Data Frame Format

Head	Mode	Length	Command	Data Segment	CRC	End
55 AA	Read/Write/Report	LENGTH	COMMAND	DATA	CRC	F0

Including,

- 1) Frame head fixed to 0x55 0xAA, frame end fixed to 0xF0;
- 2) Frame modes include reading 0x11, writing 0x16, and reporting 0x0C. Any device needs to send generic feedback instructions based on data resources when receiving writing instruction;
- 3) The total length of command segment takes 1 byte and the virtual value is 0x02~0xFF;
- 4) The command word takes 2 bytes, first of which is the order number and the second one is the length of the data segment;
- 5) The length of the data segment is LENGTH - 2;
- 6) CRC, the check bit takes 4 bytes. CAN_ID inserted between frame head and frame mode from the beginning is calculating to the last byte of the data segment. The calculation method please see appendix. The result is high byte first, for example:
When CAN_ID is 0x0712 ,the data frame is 55 AA 11 03 22 01 00 CRC1 CRC2 CRC3 CRC4 F0. CRC, the input data of calculation function is 55 AA 07 12 11 03 22 01 00, and the calculation result is written to CRC1、CRC2、CRC3、CRC4 in order from high to low;
- 7) Little-endian is adopted when the data segment is sent.

2.2.2 ID Distribution

Table 2 ID Distribution

MC	Target	Broadcast	MC	BMS	PBU	HMI	Iot Device
	CAN ID	0x710		0x712	0x713	0x714	0x715
BMS	Target	Broadcast	MC	BMS	PBU	HMI	Iot Device
	CAN ID	0x720	0x721		0x723	0x724	0x725
PBU	Target	Broadcast	MC	BMS	PBU	HMI	Iot Device

	CAN ID	0x730	0x731	0x732		0x734	0x735
HMI	Target	Broadcast	MC	BMS	PBU	HMI	Iot Device
	CAN ID	0x740	0x741	0x742	0x743		0x745
Iot Device	Target	Broadcast	MC	BMS	PBU	HMI	Iot Device
	CAN ID	0x750	0x751	0x752	0x753	0x754	

2.2.3 Encapsulation Type

For data frames with a length of more than 8bytes, subcontract them in the way of 8+N, and fill each packet with the same ID number, as shown in the following table:

Table 3 Encapsulation Way

Packet Order No.	1				N	
Content	ID	Byte1~Byte8	ID	Byte1~Byte8	ID	Byte1~ByteN

3 Communication Content

3.1 MC Command Words Definition

Table 4 MC Command Words Definition

ID	Mode	Command	Function	Data Segment	Remark
Broadcast Command					
0x710	0x0C	0x1020	MC Running information (Returned when receive control instruction from ECU)	Bike Speed: 2bytes Motor Speed: 2bytes Power Out: 2bytes Bus Voltage: 2bytes Bus Current: 2bytes Cadence: 1byte Padel Torque: 1byte Padel Direction: 1byte Assist Level: 1byte Light Switch:	0.1km/h 1rpm 1W 1mV 1mA 1rpm 1N.m 0-Forward, 1-Backward, 2-Stop 0x00:OFF 0x01:ECO 0x02:NORM 0x03:SPORT 0x04:TURBO 0x33:SMART 0xF0:OFF

				1byte SOC: 1byte Range Distance: 2bytes ODO Distance: 2bytes Power Consume: 1byte PCB Temperature: 1bytes Coil Temperature: 1bytes MCU Temperature: 1bytes Ride Distance: 2bytes Ride Time: 2byte Reserved: 4bytes	0xF1:ON 1% Invalid 0xFF 1km Invalid 0xFFFF 1km 0.01Ah/km Invalid 0xFF +40°C +40°C +40°C 0.1km 1s Fill 0x00
0x710	0x0C	0x1104	MC Fault Code (Auto sent at 200ms if there is a fault, and stop sending after the fault disappears)	double byte 32bit low 16 bit: 0x0001: OCP 0x0002: UVP 0x0004: OVP 0x0008: Rotor Lock 0x0010: OTP 0x0020: SPS Fault 0x0040: TQS Fault 0x0080: HALL Fault 0x0100: Open Phase 0x0200: NTC Fault 0x2000:	By bit or output, 0- normal, 1- fault

				MCU Fault 0x4000: Cadence Fault High 16 bit: 0x0001: MOS SC 0x0002: Voltage Abnormal 0x0004: Circuit Failure	
0x710	0x0C	0x1240	Motor version information (Return instruction)	ASCII	Sequence: MODE、SN、HW、FW; Each message is 16 bytes in length, ends with '.', and is invalid filled with 0x20. The FW are named in the format of "Vxrxxr_x_YYYYMMDD"
0x710	0x0C	0x1510	Ride history information (Return instruction)	ODO Distance: 4bytes ODO Time: 4bytes TRIP Distance: 4bytes TRIP Time: 4bytes	0.1km 1min 0.1km 1min
0x710	0x0C	0x1720	Description of particularity	ASCII	Ends with '.', and is invalid filled with 0x20.

3.2 BMS Command Word Definition

Table 5 BMS Command Word Definition

ID	Mode	Command	Function	Data Segment	Remark
Broadcast Command					
0x720	0x0C	0x1010	Battery Operating information (Return instruction)	Voltage: 2bytes Current: 2bytes RC: 2bytes FCC:	1mV 1mA, int16, Negative for discharge, Positive for charge, 1mAh 1mAh

				2bytes Cell Temperature: +40℃ 1byte SOC: 0~100% 1byte Status: 0x00: Sleep 1byte 0x01: In Charging (By bit) 0x02: RS 0x04: RS 0x08: RS 0x10: RS 0x20: RS 0x40: RS 0x80: RS Reserved: Fill 0x00 5bytes	
0x720	0x0C	0x1120	Cell voltage (Return instruction)	Cell_1:2bytes 1mV Cell_16:2bytes Invalid filled with 0x00 1mV	
0x720	0x0C	0x1204	BMS Fault Code (Auto sent at 200ms if there is a fault, and stop sending after the fault disappears)	Double byte 32bit Low 16 bit: High 16 Bits: 0x0001: Over voltage warning while in charge 0x0002: Under voltage warning while in discharge 0x0004: Over current warning while in charge 0x0008: Over current warning while in discharge 0x0010: High temperature warning while in charge	By bit or output, 0-normal, 1-fault

				0x0020: Low temperature warning while in charge 0x0040: High temperature warning while in discharge 0x0080: Low temperature warning while in discharge 0x0100: MOS high temperature warning	
0x720	0x0C	0x1308	Shutdown instructions (Actively send, after 1s stop)	ASCII	Send before go into sleep mode, delay for 1s, then shutdown.
0x720	0x0C	0x1410	Battery design information (Return instruction)	Design Capacity: 2bytes Design Voltage: 1byte Cell Mode: 8bytes Reserved: 5bytes	1mAh 1V ASCII, ends with '.', and is invalid filled with 0x20. Fill 0x00
0x720	0x0C	0x1540	Battery version information (Return instruction)	ASCII	Sequence: MODE、SN、HW、FW; Each message is 16 bytes in length, ends with '.', and is invalid filled with 0x20. The FW are named in the format of "Vxxrx_YYYYMMDD"

3.3 PBU Command Word Definition

Table 6 PBU Command Word Definition

ID	Mode	Command	Function	Data Segment	Remark
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Broadcast Command					
0x730	0x0C	0x1140	PBU Version information (Return instruction)	ASCII	Sequence: MODE、SN、HW、FW; Each message is 16 bytes in length, ends with '.', and is invalid filled with 0x20. The FW are named in the format of "Vxrxxr_YYYYMMDD"
0x730	0x0C	0x1405	Shutdown Ready (Return instruction)	ASCII	READY
0x730	0x0C	0x1504	OBC Fault code (Auto sent at 200ms if there is a fault, and stop sending after the fault disappears)	Double byte 32bit High 16 bit: Low 16 Bits: 0x0001: "+" Key fault 0x0002: "-" Key fault 0x0004: "i" Key fault 0x0008: "Light" Key fault 0x0010: "Walk" Key fault 0x0020: "Power" Key fault 0x0040: MCU fault 0x0080: MOS short circuit 0x0400: MC Communicate fault	By bit or output, 0- normal, 1-fault

3.4 HMI Command Word Definition

Table 7 HMI Command Word Definition

ID	Mode	Command	Function	Data Segment	Remark
Broadcast Command					
0x740	0x0C	0x1040	HMI Version information	ASCII	Sequence: MODE、SN、HW、FW;

			(Return instruction)		Each message is 16 bytes in length, ends with '.', and is invalid filled with 0x20. The FW are named in the format of "Vxrxxr_YYYYMMDD"
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3.5 Iot Device Command Word Definition

Table 8 Iot Device Command Word Definition

ID	Mode	Command	Function	Data Segment	Remark
Send to MC					
0x751	0x11	0x1200	Read MC version information (Actively send, after 1s stop)		
0x751	0x11	0x2E00	Read MC ride history (Actively send, after 1s stop)		
Send to BMS					
0x752	0x11	0x3300	Read BMS version information (Actively send, after 1s stop)		
0x752	0x11	0x3400	Read BMS running information (Actively send, after 1s stop)		
0x752	0x11	0x3500	Read BMS cell voltage (Actively send, after 1s stop)		
0x752	0x11	0x3600	Read BMS designed		

			information (Actively send, after 1s stop)		
Send to PBU					
0x753	0x11	0x5400	Read PBU version information (Actively send, after 1s stop)		
0x753	0x16	0x6703	Shutdown instructions (Actively send, after 1s stop)	ASCII	OFF
Send to HMI					
0x754	0x11	0x7000	Read HMI version information		

Note:

All instructions sent by CDL are sent according to the timing of 200ms, wherein the query instruction will stop sending after receiving the returned information or timeout for 1s, and the write instruction will stop sending after receiving the general feedback instruction or timeout for 1s.

4 Appendix 1: CRC32 Calculating Method

4.1 CRC32 Table of calculating polynomials

```
uint32_t Crc32Table[ 256 ] =
```

```
{
```

```
    0x00000000, 0x04C11DB7, 0x09823B6E, 0x0D4326D9, 0x130476DC, 0x17C56B6B,
    0x1A864DB2, 0x1E475005, 0x2608EDB8, 0x22C9F00F, 0x2F8AD6D6, 0x2B4BCB61,
    0x350C9B64, 0x31CD86D3, 0x3C8EA00A, 0x384FBDBD, 0x4C11DB70, 0x48D0C6C7,
    0x4593E01E, 0x4152FDA9, 0x5F15ADAC, 0x5BD4B01B, 0x569796C2, 0x52568B75,
    0x6A1936C8, 0x6ED82B7F, 0x639B0DA6, 0x675A1011, 0x791D4014, 0x7DDC5DA3,
    0x709F7B7A, 0x745E66CD, 0x9823B6E0, 0x9CE2AB57, 0x91A18D8E, 0x95609039,
    0x8B27C03C, 0x8FE6DD8B, 0x82A5FB52, 0x8664E6E5, 0xBE2B5B58, 0xBAEA46EF,
    0xB7A96036, 0xB3687D81, 0xAD2F2D84, 0xA9EE3033, 0xA4AD16EA, 0xA06C0B5D,
    0xD4326D90, 0xD0F37027, 0xDDB056FE, 0xD9714B49, 0xC7361B4C, 0xC3F706FB,
    0xCEB42022, 0xCA753D95, 0xF23A8028, 0xF6FB9D9F, 0xFBB8BB46, 0xFF79A6F1,
    0xE13EF6F4, 0xE5FFE643, 0xE8BCCD9A, 0xEC7DD02D, 0x34867077, 0x30476DC0,
    0x3D044B19, 0x39C556AE, 0x278206AB, 0x23431B1C, 0x2E003DC5, 0x2AC12072,
    0x128E9DCF, 0x164F8078, 0x1B0CA6A1, 0x1FCDBB16, 0x018AEB13, 0x054BF6A4,
    0x0808D07D, 0x0CC9CDCA, 0x7897AB07, 0x7C56B6B0, 0x71159069, 0x75D48DDE,
    0x6B93DDDB, 0x6F52C06C, 0x6211E6B5, 0x66D0FB02, 0x5E9F46BF, 0x5A5E5B08,
    0x571D7DD1, 0x53DC6066, 0x4D9B3063, 0x495A2DD4, 0x44190B0D, 0x40D816BA,
    0xACA5C697, 0xA864DB20, 0xA527FDF9, 0xA1E6E04E, 0xBFA1B04B, 0xBB60ADFC,
    0xB6238B25, 0xB2E29692, 0x8AAD2B2F, 0x8E6C3698, 0x832F1041, 0x87EE0DF6,
    0x99A95DF3, 0x9D684044, 0x902B669D, 0x94EA7B2A, 0xE0B41DE7, 0xE4750050,
    0xE9362689, 0xEDF73B3E, 0xF3B06B3B, 0xF771768C, 0xFA325055, 0xFEF34DE2,
    0xC6BCF05F, 0xC27DEDE8, 0xCF3ECB31, 0xCBFFD686, 0xD5B88683, 0xD1799B34,
    0xDC3ABDED, 0xD8FBA05A, 0x690CE0EE, 0x6DCDFD59, 0x608EDB80, 0x644FC637,
    0x7A089632, 0x7EC98B85, 0x738AAD5C, 0x774BB0EB, 0x4F040D56, 0x4BC510E1,
    0x46863638, 0x42472B8F, 0x5C007B8A, 0x58C1663D, 0x558240E4, 0x51435D53,
    0x251D3B9E, 0x21DC2629, 0x2C9F00F0, 0x285E1D47, 0x36194D42, 0x32D850F5,
    0x3F9B762C, 0x3B5A6B9B, 0x0315D626, 0x07D4CB91, 0x0A97ED48, 0x0E56F0FF,
    0x1011A0FA, 0x14D0BD4D, 0x19939B94, 0x1D528623, 0xF12F560E, 0xF5EE4BB9,
    0xF8AD6D60, 0xFC6C70D7, 0xE22B20D2, 0xE6EA3D65, 0xEBA91BBC, 0xEF68060B,
    0xD727BBB6, 0xD3E6A601, 0xDEA580D8, 0xDA649D6F, 0xC423CD6A, 0xC0E2D0DD,
    0xCDA1F604, 0xC960EBB3, 0xBD3E8D7E, 0xB9FF90C9, 0xB4BCB610, 0xB07DABA7,
    0xAE3AFBA2, 0xAAFBE615, 0xA7B8COCC, 0xA379DD7B, 0x9B3660C6, 0x9FF77D71,
    0x92B45BA8, 0x9675461F, 0x8832161A, 0x8CF30BAD, 0x81B02D74, 0x857130C3,
    0x5D8A9099, 0x594B8D2E, 0x5408ABF7, 0x50C9B640, 0x4E8EE645, 0x4A4FFBF2,
    0x470CDD2B, 0x43CDC09C, 0x7B827D21, 0x7F436096, 0x7200464F, 0x76C15BF8,
    0x68860BFD, 0x6C47164A, 0x61043093, 0x65C52D24, 0x119B4BE9, 0x155A565E,
    0x18197087, 0x1CD86D30, 0x029F3D35, 0x065E2082, 0x0B1D065B, 0x0FDC1BEC,
    0x3793A651, 0x3352BBE6, 0x3E119D3F, 0x3AD08088, 0x2497D08D, 0x2056CD3A,
    0x2D15EBE3, 0x29D4F654, 0xC5A92679, 0xC1683BCE, 0xCC2B1D17, 0xC8EA00A0,
    0xD6AD50A5, 0xD26C4D12, 0xDF2F6BCB, 0xDBEE767C, 0xE3A1CBC1, 0xE760D676,
```

```
0xEA23F0AF, 0xEE2ED18, 0xF0A5BD1D, 0xF464A0AA, 0xF9278673, 0xFDE69BC4,  
0x89B8FD09, 0x8D79E0BE, 0x803AC667, 0x84FBDBD0, 0x9ABC8BD5, 0x9E7D9662,  
0x933EB0BB, 0x97FFAD0C, 0xAFB010B1, 0xAB710D06, 0xA6322BDF, 0xA2F33668,  
0xBCB4666D, 0xB8757BDA, 0xB5365D03, 0xB1F740B4  
};
```

4.2 CRC32 Calculating Method

```
uint32_t CRC32_Calculate( uint8_t *pData, uint16_t Length )  
{  
    uint32_t nReg;  
    uint32_t nTemp = 0;  
    uint16_t i, n;  
  
    nReg = 0xFFFFFFFF;  
    for ( n = 0; n < Length; n++ )  
    {  
        nReg ^= (uint32_t) pData[ n ];  
        for ( i = 0; i < 4; i++ )  
        {  
            nTemp = Crc32Table[ ( uint8_t )( ( nReg >> 24 ) & 0xFF ) ];  
            nReg <<= 8;  
            nReg ^= nTemp;  
        }  
    }  
    return nReg;  
}
```

5 Appendix 2: Development Consideration

1) When MC, PBU, or BMS fails, it will proactively send fault codes at timing of 200ms, at this time, there will be large data in the CAN bus;

2) Besides the fault code, MC and BMS will not actively send other instructions.

3) When the system is working, the PBU sends the query data to the MC and BMS at a time of 200ms, and so the Iot device can get the running information of MC and BMS automaticly;

4) It is not all the commands should be designed, just according to the required function;

5) When need to power off the system, the Iot device should send the shutdown command to PBU refer to Table 8.